CHAPTER 14 GRAPH ALGORITHMS

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GRAPH

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• A graph is a pair G = (V, E), where

- V is a set of nodes, called vertices
- E is a collection of pairs of vertices, called edges
- Vertices and edges can store arbitrary elements
- Example:
 - A vertex represents an airport and stores the three-letter airport code
 - An edge represents a flight route between two airports and stores the mileage of the route



APPLICATIONS

• Electronic circuits

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- Printed circuit board
- Integrated circuit
- Transportation networks
 - Highway network
 - Flight network
- Computer networks
 - Local area network
 - Internet
 - Web

Databases

Entity-relationship diagram



TERMINOLOGY EDGE AND GRAPH TYPES

• Edge Types

(u, v)

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- Directed edge
 - ordered pair of vertices (u, v)
 - first vertex u is the origin/source
 - second vertex v is the destination/target
 - e.g., a flight
- Undirected edge
 - unordered pair of vertices (u, v)
 - e.g., a flight route

ORD

U

- Weighted edge
 - Numeric label associated with edge

flight

AA 1206 802 miles DFW

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- Graph Types
 - **Directed** graph (Digraph)
 - all the edges are directed
 - e.g., route network
 - Undirected graph
 - all the edges are undirected
 - e.g., flight network
 - Weighted graph
 - all the edges are weighted



TERMINOLOGY VERTICES AND EDGES

- **End points** (or end vertices) of an edge
 - U and V are the endpoints of a
- Edges incident on a vertex
 - a, d, and b are incident on V
- Adjacent vertices

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- *U* and *V* are adjacent
- **Degree** of a vertex
 - X has degree 5
- Parallel (multiple) edges
 - *h* and *i* are parallel edges
- Self-loop
 - *j* is a self-loop



Note: A graph with no parallel edges or self loops are said to be simple. Unless otherwise stated, you should assume all graphs discussed are simple

TERMINOLOGY VERTICES AND EDGES

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- Outgoing edges of a vertex
 - h and b are the outgoing edges of X
- Incoming edges of a vertex
 - e, g, and i are incoming edges of X
- In-degree of a vertex
 - X has in-degree 3
- Out-degree of a vertex
 - X has out-degree 2



TERMINOLOGY PATHS

Path

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- Sequence of alternating vertices and edges
- Begins with a vertex
- Ends with a vertex
- Each edge is preceded and followed by its endpoints

• Simple path

- Path such that all its vertices and edges are distinct
- Examples
 - $P_1 = \{V, b, X, h, Z\}$ is a simple path
 - $P_2 = \{U, c, W, e, X, g, Y, f, W, d, V\}$ is a path that is not simple



TERMINOLOGY CYCLES

Cycle

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- Circular sequence of alternating vertices and edges
- Each edge is preceded and followed by its endpoints

• Simple cycle

- Cycle such that all its vertices and edges are distinct except for the beginning and ending vertex
- Examples
 - $C_1 = \{V, b, X, g, Y, f, W, c, U, a, V\}$ is a simple cycle
 - $C_2 = \{U, c, W, e, X, g, Y, f, W, d, V, a, U\}$ is a cycle that is not simple
- A digraph is called **acyclic** if it does not contain any cycles



EXERCISE ON TERMINOLOGY

1. Number of vertices?

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- 2. Number of edges?
- 3. What type of the graph is it?
- 4. Show the end vertices of the edge with largest weight
- 5. Show the vertices of smallest degree and largest degree
- 6. Show the edges incident to the vertices in the above question
- 7. Identify the shortest simple path from HNL to PVD
- 8. Identify the simple cycle with the most edges



EXERCISE PROPERTIES OF UNDIRECTED GRAPHS

• Property 1 – Total degree $\Sigma_v deg(v) = ?$

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- Property 2 Total number of edges
 - In an undirected graph with no selfloops and no multiple edges
 m ≤ Upper Bound?
 Lower Bound? ≤ m

Notation

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- n number of vertices
- m number of edges
- deg(v) degree of vertex v



EXERCISE PROPERTIES OF UNDIRECTED GRAPHS

Property 1 – Total degree $\Sigma_v deg(v) = 2m$

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- Property 2 Total number of edges
 - In an undirected graph with no self-loops and no multiple edges

 $m \le \frac{n(n-1)}{2}$ $0 \le m$

Proof: Each vertex can have degree at most (n-1)

Notation

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- n
 - *m* number of edges
- deg(*v*)
- degree of vertex v

number of vertices



EXERCISE PROPERTIES OF DIRECTED GRAPHS

 Property 1 – Total in-degree and outdegree

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- $\Sigma_v in \deg(v) =?$ $\Sigma_v out - \deg(v) =?$
- Property 2 Total number of edges
 In an directed graph with no self-loops and no multiple edges m ≤ UpperBound? LowerBound? ≤ m

- Notation
 - n
 - *m*
- number of vertices
- number of edges
- deg(v) degree of vertex v



A graph with given number of vertices (4) and maximum number of edges

EXERCISE PROPERTIES OF DIRECTED GRAPHS

 Property 1 – Total in-degree and outdegree

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- $\Sigma_{v}in \deg(v) = m$ $\Sigma_{v}out - \deg(v) = m$
- Property 2 Total number of edges
 - In an directed graph with no self-loops and no multiple edges $m \le n(n-1)$ $0 \le m$

- Notation
 - n
 - *m*
- number of vertices number of edges
- deg(v) degree of vertex v



- n = 4
 - *m* = 12
 - $\deg(v) = 6$

A graph with given number of vertices (4) and maximum number of edges

TERMINOLOGY CONNECTIVITY

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- Given two vertices u and v, we say u
 reaches v, and that v is reachable from u, if there exists a path from u to v. In an undirected graph reachability is symmetric
- A graph is connected if there is a path between every pair of vertices
- A digraph is strongly connected if there
 every pair of vertices is reachable

Connected graph u and v are reachable

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u and v are not mutually reachable

TERMINOLOGY SUBGRAPHS

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- A subgraph H of a graph G is a graph whose vertices and edges are subsets of G, respectively
- A spanning subgraph of G is a subgraph that contains all the vertices of G
- A connected component of a graph G is a maximal connected subgraph of G



TERMINOLOGY TREES AND FORESTS

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- A forest is a graph without cycles
- A (free) tree is connected forest
 - This definition of tree is different from the one of a rooted tree
- The connected components of a forest are trees



Forest

SPANNING TREES AND FORESTS

• A spanning tree of a connected graph is a spanning subgraph that is a tree

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- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks



GRAPH ADT

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- Vertices and edges are lightweight objects and store elements
- Although the ADT is specified from the graph object, we often have similar functions in the Vertex and Edge objects

- numVertices(): Returns the number of vertices of the graph.
 vertices(): Returns an iteration of all the vertices of the graph.
 numEdges(): Returns the number of edges of the graph.
 edges(): Returns an iteration of all the edges of the graph.
- getEdge(u, v): Returns the edge from vertex u to vertex v, if one exists; otherwise return null. For an undirected graph, there is no difference between getEdge(u, v) and getEdge(v, u).
- endVertices(e): Returns an array containing the two endpoint vertices of edge e. If the graph is directed, the first vertex is the origin and the second is the destination.
- opposite(v, e): For edge *e* incident to vertex *v*, returns the other vertex of the edge; an error occurs if *e* is not incident to *v*.

outDegree(v): Returns the number of outgoing edges from vertex v.

inDegree(v): Returns the number of incoming edges to vertex v. For an undirected graph, this returns the same value as does outDegree(v).

outgoingEdges(v): Returns an iteration of all outgoing edges from vertex v.

incomingEdges(v): Returns an iteration of all incoming edges to vertex v. For an undirected graph, this returns the same collection as does outgoingEdges(v).

insertVertex(x): Creates and returns a new Vertex storing element x.

insertEdge(u, v, x): Creates and returns a new Edge from vertex u to vertex v, storing element x; an error occurs if there already exists an edge from u to v.

removeVertex(v): Removes vertex v and all its incident edges from the graph.
removeEdge(e): Removes edge e from the graph.

EXERCISE ON ADT

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1.outgoingEdges(ord)
2.incomingEdges(ord)
3.outDegree(ord)
4.endVertices({lga,mia})
5.opposite(dfw,{dfw,lga})

6.insertVertex(iah)
7.insertEdge(mia, pvd, 1200)
8.removeVertex(ord)
9.removeEdge({dfw,ord})



EDGE LIST STRUCTURE

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- An edge list can be stored in a list or a map/dictionary (e.g. hash table)
- Vertex object
 - element
 - reference to position in vertex sequence
- Edge object
 - element
 - origin vertex object
 - destination vertex object
 - reference to position in edge sequence

EXERCISE EDGE LIST STRUCTURE

• Construct the edge list for the following graph



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ASYMPTOTIC PERFORMANCE EDGE LIST STRUCTURE

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			Edge List	Vertex L
	 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Edge List	 ◆ {ORD, PVD, 849} ◆ {ORD, DFW, 802} 	ORD LGA
	Space	?		
	<pre>getEdge(u,v), outDegree(v), outgoingEdges(v), insertEdge(u,v,w), removeVertex(v)</pre>	?	 {LGA, MIA, 1099} {DFW, LGA, 1387} {DFW, MIA, 1120} 	DFW
\rightarrow	<pre>insertVertex(x), removeEdge(e)</pre>	?		

ASYMPTOTIC PERFORMANCE EDGE LIST STRUCTURE

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		Edge List	Vertex List
 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Edge List	 {ORD, PVD, 849} {ORD, DFW, 802} 	LGA •
Space	O(n+m)	{I GA, PVD, 142}	
<pre>getEdge(u,v), outDegree(v), outgoingEdges(v), insertEdge(u,v,w), removeVertex(v)</pre>	0(m)	 {LGA, MIA, 1099} {DFW, LGA, 1387} {DFW, MIA, 1120} 	DFW MIA
<pre>insertVertex(x), removeEdge(e)</pre>	0(1)		





- Adjacency Lists associate vertices with their edges (in addition to edge list!)
- Each vertex stores a list of incident edges
 - List of references to incident edge objects
- Augmented edge object
 - Stores references to associated positions in incident adjacency lists

EXERCISE ADJACENCY LIST STRUCTURE

• Construct the adjacency list for the following graph



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ASYMPTOTIC PERFORMANCE ADJACENCY LIST STRUCTURE

 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Adjacency List	Adjacency List
Space	?	LGA (LGA, PVD) (LGA, MIA) (LGA, DFW)
getEdge(<i>u,v</i>), insertEdge(<i>u,v,w</i>)	?	<pre>OPVD H{PVD, ORD} H{PVD, LGA} OPDFW {DFW, ORD} {DFW, LGA} {DFW, MIA}</pre>
<pre>outDegree(v), insertVertex(x), removeEdge(e)</pre>	?	MIA {MIA, LGA} -{MIA, DFW}
<pre>outgoingEdges(v), removeVertex(v)</pre>	?	

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ASYMPTOTIC PERFORMANCE ADJACENCY LIST STRUCTURE

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 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Adjacency List	Adjacency List
Space	O(n+m)	
getEdge(<i>u,v</i>), insertEdge(<i>u,v,w</i>)	$O(\min(\deg(v), \deg(u)))$	PVD H{PVD, ORD} H{PVD, LGA} DFW H{DFW, ORD} H{DFW, LGA} H{DFW, MIA}
<pre>outDegree(v), insertVertex(x), removeEdge(e)</pre>	0(1)	MIA {MIA, LGA} {MIA, DFW}
<pre>outgoingEdges(v), removeVertex(v)</pre>	$O(\deg(v))$	

ADJACENCY MAP STRUCTURE

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- We can store augmenting incidence structures in maps, instead of lists. This is called an adjacency map.
 - In general an "adjacency list" means storing adjacency with vertices, so the terms are interchangeable
- What would this do to the complexities?
 - If it is implemented as a hash table?
 - If it is implemented as a red-black tree?



	0	1	2	3	4
0	Ø	Ø	{0, 2}	{0, 3}	Ø
1	Ø	Ø	{1, 2}	{1, 3}	{1, 4}
2	{0, 2}	{1, 2}	Ø	Ø	Ø
3	{0, 3}	{1, 3}	Ø	Ø	{3, 4}
4	Ø	{1, 4}	Ø	{3, 4}	Ø

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- Adjacency matrices store references to edges in a table (in addition to the edge list)
- Augment vertices with integer keys (often done in all graph implementations!)

EXERCISE ADJACENCY MATRIX STRUCTURE

• Construct the adjacency matrix for the following graph



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ASYMPTOTIC PERFORMANCE ADJACENCY MATRIX STRUCTURE

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 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Adjacency Matrix
Space	?
outDegree(v), $outgoingEdges(v)$?
getEdge(<i>u,v</i>), insertEdge(<i>u,v,w</i>), removeEdge(<i>e</i>)	?
insertVertex (x) , removeVertex (v)	?

	0	1	2	3	4
)	Ø	Ø	{0, 2}	{0, 3}	Ø
<u> </u>	Ø	Ø	{1, 2}	{1, 3}	{1, 4}
2	{0, 2}	{1, 2}	Ø	Ø	Ø
3	{0, 3}	{1, 3}	Ø	Ø	{3, 4}
}	Ø	{1, 4}	Ø	{3, 4}	Ø

ASYMPTOTIC PERFORMANCE ADJACENCY MATRIX STRUCTURE

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 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Adjacency Matrix	
Space	$O(n^2)$	
<pre>outDegree(v), outgoingEdges(v)</pre>	O(n)	
getEdge(<i>u,v</i>), insertEdge(<i>u,v,w</i>), removeEdge(<i>e</i>)	0(1)	
insertVertex (x) , removeVertex (v)	$O(n^2)$	

	0	1	2	3	4
)	Ø	Ø	{0, 2}	{0, 3}	Ø
	Ø	Ø	{1, 2}	{1, 3}	{1, 4}
2	{0, 2}	{1, 2}	Ø	Ø	Ø
;	{0, 3}	{1, 3}	Ø	Ø	{3, 4}
•	Ø	{1, 4}	Ø	{3, 4}	Ø

ASYMPTOTIC PERFORMANCE

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 <i>n</i> vertices, <i>m</i> edges No parallel edges No self-loops 	Edge List	Adjacency List	Adjacency Matrix
Space	O(n+m)	O(n+m)	$O(n^2)$
outgoingEdges (v)	O(m)	$O(\deg(v))$	O(n)
getEdge(<i>u,v</i>)	O(m)	$O(\min(\deg(v), \deg(w)))$	O(1)
insertEdge(<i>u,v,w</i>)	O(m)	$O(\min(\deg(v), \deg(w)))$	O(1)
eraseEdge(<i>e</i>)	0(1)	0(1)	O(1)
insertVertex(x)	0(1)	0(1)	$O(n^2)$
removeVertex($ u$)	O(m)	$O(\deg(v))$	$O(n^2)$